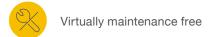




Servo pillar CPSM











Servo pillar CPSM



Features

- High dynamic servo or brushless DC motor for high speed up to 100 mm/s
- High performance ball screw for high load capacity up to 5 kN
- Extruded alumium proiles for a very robust design
- Manually adjusted gliders for very high stiffness and high excentric loads
- Encoder system of the motor and high quality gearbox enable high positioning accuracy and high repeatability (0,1 mm)

Benefits

- High nominal power of the motor allows for high duty cycle of the pillar
- Customized motor adapter for highest flexibility (max. motor diameter 90 mm)
- Customized top and bottom plate to fit most of the applications
- Customized aluminum profile colour (anodized) to fit application design needs
- Optional brake to release the motor when it's in position and to increase the duty cycle
- Preloaded bearing arrangement also for ceiling mount applications (only available without damping system)



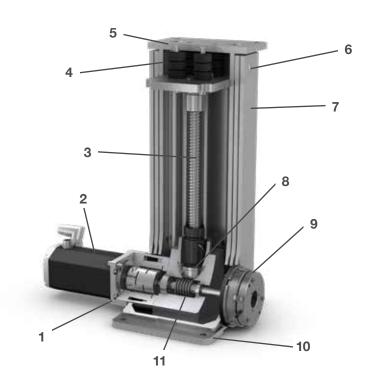
Product description

Telescopic pillars CPSM are the ideal solution to combine strong guiding functions with linear movements.

The robust, manually adjusted and virtually backlash-free aluminum extrusions are able to carry high excentric loads in push and pull directions.

To provide enough power to lift and lower heavy weights with high speed, the pillars are equipped with brushless DC or servo motors. Of course, Ewellix also supports the usage of preferred motors with a customizable motor interface.

Optional brakes and damping elements are key features that allow an effective usage in heavy duty industrial applications.



- 1. Standard or customized motor interface
- 2. Motor (Brushless DC or servo AC)
- 3. High eficiency ball screw
- 4. Optional damping system
- 5. Customized top plate
- 6. Backlash-free long lasting guiding pads
- 7. 2 or 3 section extruded aluminum guiding tubes
- 8. Preloaded bearing arrangement
- 9. Optional electromechanical brake
- 10. Customized bottom plate
- 11. Low friction worm gear reduction



CPSM

Servo pillar



Technical data

Designation	Symbol	Unit	w/o motor	BG75	1FK7034
Performance Data					
Continuous force @ zero speed	F _{c0}	kN	5	4,013	5
Continuous force @ max. speed	F _c	kN	5	4,013	4,013
Peak force @ zero speed	'c F	kN	5	5	5
•	F _{p0}	kN	5	5	5
Peak force @ max. speed	F _p		21	21	21
Dynamic load capacity	С	kN			
olding force (motorbrake option)	F _{Hold-MB}	kN	N/A	5	5
Holding force (external brake option)	r _{Hold-EB}	kN	5	5	5
Max. linear speed	V _{max}	mm/s	-	62	100
Max. acceleration	a _{max}	m/s²	6	6	6
Outy cycle	D	%	100	100	100
Mechanical Data					
Screw type		_	Ball screw	Ball screw	Ball screw
crew type crew diameter	_	mm	20	20	20
crew diameter	d _{screw}	mm	10	10	10
	p _{screw}	-	G7	G7	G7
ead accuracy troke ¹⁾			100700	100700	100700
troke ² ternal overstroke each side	S	mm	100700	1	1
acklash	S ₀	mm	0,07	0,07	0,07
acklash ear reduction	S _{backlash}	mm -	10	10	10
		%	58	52	51
fficiency	η	70	56	52	31
lectrical Data					
Motor type	-	-	N/A	Brushless DC	Servo
Iominal voltage	U	V DC	N/A	40	N/A
ominal current	I	Α	N/A	12,7	1,3
eak current	l _{peak}	Α	N/A	10,8	1,9
ominal power	P	kW	N/A	0,45	0,6
Invironment	_	00	0 .50	0 . 50	0 . 50
ambient temperature	Tambient	°C	0+50	0+50	0+50
Max. humidity	ф	%	95	95	95

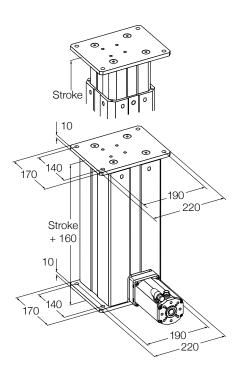
¹⁾ By 100 mm steps

Ordering key

See page 9

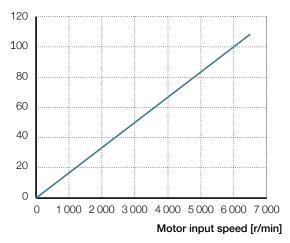


Dimensional drawing



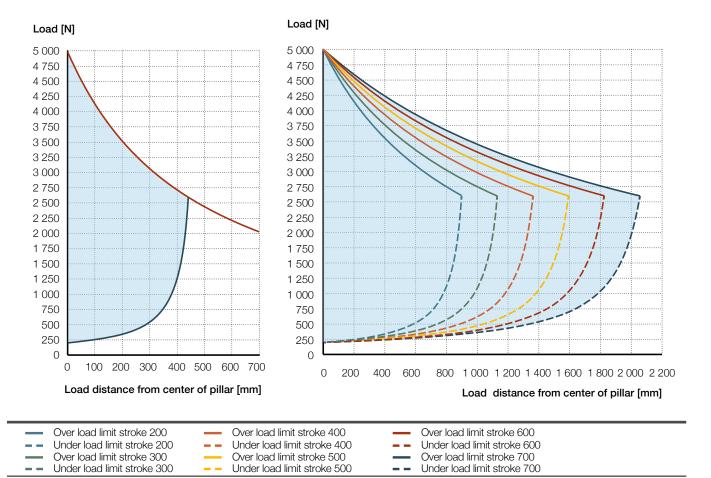
Performance diagram

Pillar output speed [mm/s]





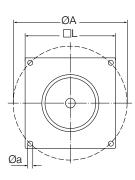
Performance diagrams

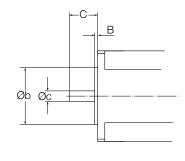




Adapter for third-party motors

In order to attach your preferred motor to the pillar, Ewellix offers tailormadesolutions within the specifications below. For motor specifications which are not covered by those below, please contact Ewellix.



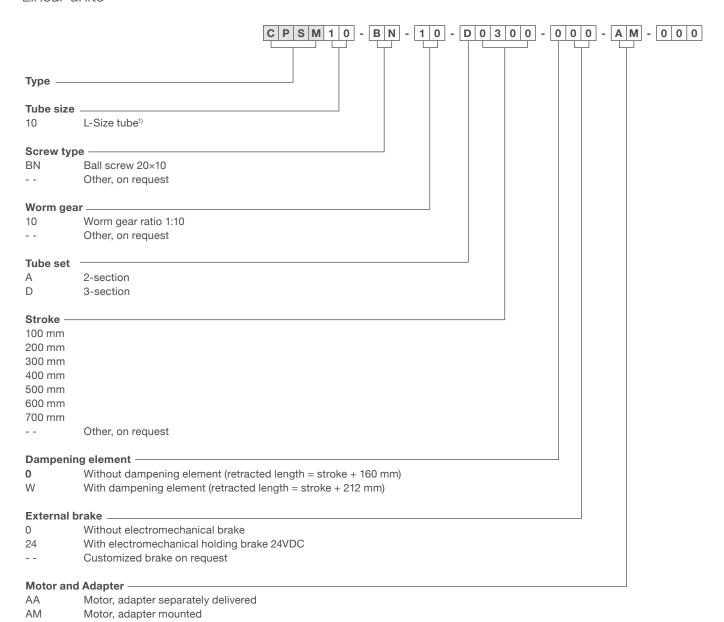


Designation	Symbol	Unit	Min.	Max.
Motor housing	□L	mm	60	95
Motor centering	Øb	mm	47	95
Centering height	В	mm	1	5
Fixing diameter	ØA	mm	52	103
Shaft diameter	Øc	mm	11	19
Shaft lenght	С	mm	15	48



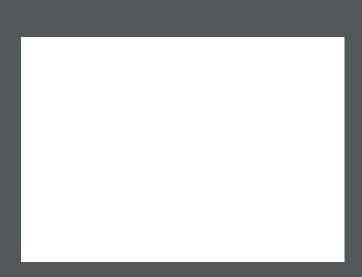
Ordering key

Linear units



 $^{1)}3\text{-}$ sections: \square 163 mm / 2-sections: \square 146 m

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